

DIE SET FOR PRESS FORMING METAL SHEET AND PRESS FORMING METHOD OF METAL SHEET

BACKGROUND OF THE INVENTION

Field of the invention

The present invention relates to a die set for press forming a metal sheet such as a sheet steel or an aluminum sheet mainly applicable to an automobile body, and a press forming method using such a die set. More particularly, it relates to a die set for press forming and a press forming method, each capable of minimizing the occurrence of dimensional accuracy defect of a formed product caused by elastic recovery after release from the die set in press forming.

Description of Related Art

In the motor vehicle related industry, high strength materials tend to be increasingly used because of a growing demand for an improvement of the crash safety of an automobile body and environmental protection (improvement of fuel economy due to a reduction in weight). A large number of parts of an automobile body are generally manufactured by press forming metal sheets. However, when these parts are formed by press forming, the shape (dimension) of the resulting formed product varies from the designed value due to the elastic recovery behavior after release from the die set (taking out from the die set after forming), which may cause deficiencies at the time of assembling of parts or at the time of bonding (often, bonding by spot welding). Such deficiencies are generically referred

to as dimensional accuracy defects. As such dimensional accuracy defects, various ones such as wall warp and angle change are known (see, e.g., "Press Forming Relative Difficulty Handbook" second edition (1997), pages 175 to 196, THE NIKKAN KOGYO SHIMBUN, LTD.).

In recent years, with the growing opportunities to use a sheet steel having higher strength, and an aluminum sheet having a smaller weight than that of a sheet steel, but having a low Young's modulus for an automobile body from the viewpoints of a reduction in weight and the stability of the automobile body, the foregoing dimensional accuracy defect has become a noticeable problem.

FIG. 1 is an explanatory diagram showing an outside shape example of a hat channel member as an automotive part. Such a hat channel member is mainly formed by a draw forming method [FIG. 2A] and a bend forming method [FIG. 2B].

One example of the dimensional accuracy defect when a hat channel member was formed using a die set (a die set for draw forming) shown in FIG. 2A will be described by reference to FIGS. 3A and 3B. FIGS. 3A and 3B each show a product cross sectional shape when a 980 MPa class cold rolled sheet steel (thickness t : 1.2 mm) has been formed. It is indicated that the shape after press forming [FIG. 3B] largely deviates from the objective dimensions. Namely, when the designed (objective) shape (axially perpendicular cross sectional shape) of the hat channel member is assumed to be the one shown in FIG. 3A, the flange surface to be bonded to other parts by spot welding or

the like, and to be required to have a close dimensional accuracy springs up by as much as 48° (this spring up angle will be referred to as a "flange spring angle θ ", below). This is considered to be caused by the effects of both the angle change defect at a punch shoulder and the wall warp defect at a sidewall portion [FIG. 3B]

It is explained that the occurrence mechanism of the wall warp arising at the sidewall portion of the hat channel member is due to the following mechanisms (1) to (3) (see the aforesaid document).

(1) The material (metal sheet) undergoes bending deformation when passing through the die radius portion;

(2) When this portion flows from the die radius portion to the sidewall portion, it undergoes bending-back deformation to be stretched in a straight line, and at this step, a difference between stresses of opposite signs occurs along the sheet thickness direction at the sidewall portion, so that the bending moment due to the difference in stress inherently exists; and

(3) When the resulting formed product is released from the die set after forming, elastic recovery is generated so as to release the bending moment, and as a result, warp occurs.

As techniques for reducing such a wall warp phenomenon, various proposals have been made heretofore. As one of such techniques, there is known a method utilizing the reverse bending in a die gap (between a die and a punch (see, the Non-patent Document 1)). The mechanism for wall warp reduction in the case where this method is applied is described as follows.

First, as with general forming, when a material passes through the die radius portion, it undergoes bending deformation. However, when this portion flows from the die radius portion to the sidewall portion, there may occur a phenomenon that the material does not completely wind around the die radius portion according to setting of the size of the die radius and the clearance (the gap between the punch and the die). This phenomenon is generally referred to as overrun. The material which has flown to the sidewall portion due to this phenomenon undergoes bending in a reverse direction to the foregoing bending direction (generally referred to as reverse bending).

Then, when the material is released from the die set after forming, elastic recovery occurs so as to release the bending moment as with general forming. However, the elastic recovery at this step acts in a direction to cancel out the foregoing resultant reverse bending. For this reason, when the curvature of reverse bending and the curvature generated due to elastic recovery become equal to each other, these cancel out each other. As a result, it becomes possible to set the curvature of the sidewall portion (=wall warp) to 0.

As a method for controlling the wall warp by utilizing the overrun, there is conventionally known a method in which the die radius and the clearance are properly controlled. However, with such a technique, the die radius and the clearance are required to be controlled accurately in order to entirely eliminate the wall warp. Particularly, the technique will not

exert its effects unless the die radius (rd) is controlled at rd/t (t: thickness) = about 1.5 (see the aforesaid document). The thickness t of the sheet steel generally used for automotive structural parts is about 1 mm. Thus, in order for the technique to effectively exert its effects, it is essential that the die radius (rd) is set at about 1.5 mm.

However, when the die radius (rd) is reduced, unfavorably, the risk of the occurrence of cracking during forming increases so much, and tools become more likely to wear, which necessitates the maintenance of the tools to be frequently performed. These problems can also be said to be destabilizing factors in actual production. For this reason, the foregoing method is unfavorably less applicable to mass production.

SUMMARY OF THE INVENTION

Under such circumstances, the present invention has been completed. It is therefore an object of the present invention to implement a die set for press forming capable of stably generating a reverse bending deformed portion due to overrun even when a die radius is large, minimizing the phenomenon such as wall warp, and enhancing dimensional accuracy in press forming of a metal sheet, and a press forming method using the die set.

A die set for press forming a metal sheet according to one aspect of the present invention, capable of achieving the foregoing object, is a die set for press forming a metal sheet, which comprises: at least a punch; and a die, characterized in

that a clearance CL2 between the punch and the die corresponding to a site to be formed immediately after an initial stage of press forming is at least set wider than a clearance CL1 between the punch and the die corresponding to a site to be formed in the initial stage of press forming ($CL1 < CL2$).

In the die set, the clearances CL1 and CL2 are set so as to satisfy the following expressions (1) and (2), respectively:

$$0.8 \times t \leq CL1 \leq 1.2 \times t \quad \cdots (1)$$

$$CL2 \geq CL1 + t \quad \cdots (2)$$

where t denotes a thickness of the metal sheet to be formed.

The die set of the present invention is additionally configured as follows. The die set for press forming a metal sheet further comprises a forming jig which moves in synchronism with the die while keeping the relative position to the die during forming, and forms the vertical wall portion of the metal sheet, wherein in the forming jig, a clearance CL4 between the forming jig and the die in the vicinity of a die shoulder is set so as to be wider than a clearance CL3 between the forming jig and the die in the forming area other than the vicinity of the die shoulder ($CL3 < CL4$). As a result, it is possible to further enhance the dimensional accuracy for press forming of a metal sheet.

Whereas, in such a die set, it is preferable that the clearances CL3 and CL4 are set so as to satisfy the following expressions (3) and (4), respectively:

$$0.8 \times t \leq CL3 \leq 1.2 \times t \quad \cdots (3)$$

$$CL4 \geq CL3 + t \quad \cdots (4)$$

where t denotes the thickness of the metal sheet to be formed.

Further, even when the die set of the present invention is configured such as not to have the clearances $CL1$ and $CL2$ provided, and have only the clearances $CL3$ and $CL4$, if required, it is possible to achieve the object of the present invention. Namely, in accordance with another aspect of the present invention, a die set comprising at least a punch and a die, for press forming a metal sheet, and thereby manufacturing a formed product having an inclined vertical wall portion, comprises a forming jig which moves in synchronism with the die while keeping the relative position to the die during forming, and forms the inclined vertical wall portion of the metal sheet, characterized in that in the forming jig, a clearance $CL4$ between the forming jig and the die in the vicinity of the die shoulder is set so as to be wider than a clearance $CL3$ between the forming jig and the die in the forming area other than the vicinity of the die shoulder ($CL3 < CL4$).

Even when such a die set configuration is adopted, the clearances $CL3$ and $CL4$ are preferably set so as to satisfy the expressions (3) and (4), respectively.

By press forming metal sheets by means of the foregoing various die sets for press forming, it is possible to obtain metal press formed products excellent in dimensional accuracy without causing disadvantages such as wall warp and angle change.

The present invention is constituted as described above.

It is possible to implement a die set for press forming capable of stably generating overrun even when the die radius r_d is large, minimizing the phenomenon such as wall warp or angle change, and enhancing the dimensional accuracy in press forming of the metal sheet, and a press forming method using the die set.

BRIEF DESCRIPTION OF THE DRAWINGS

FIG. 1 is an explanatory diagram showing an outside shape example of a hat channel member;

FIGS. 2A and 2B are schematic explanatory diagrams each showing a main forming method of the hat channel member;

FIGS. 3A and 3B are diagrams for illustrating one example of dimensional accuracy defects;

FIG. 4 is a schematic explanatory diagram showing one example of a configuration of a press forming die set of the present invention;

FIGS. 5A and 5B are schematic explanatory diagrams showing various shapes of the die sets of the present invention;

FIGS. 6A to 6C are schematic explanatory diagrams showing the product cross sectional shapes when press forming has been performed under the conditions of various clearances CL_1 ;

FIG. 7 is a diagram for illustrating the state in which forming is started with a blank holder waiting;

FIG. 8 is a diagram for illustrating the conditions of occurrence of overrun when forming has been performed with the blank holder waiting;

FIGS. 9A and 9B are explanatory diagrams each showing the

state of the die set at the time of start of forming;

FIG. 10 is an explanatory diagram showing the state in which forming of a metal sheet has been completed (forming bottom dead center);

FIG. 11 is a diagram for illustrating the state in which the overrun caused to the metal sheet is further amplified;

FIGS. 12A and 12B are diagrams for illustrating the state in which reverse bending occurs in the lower part 4a of the metal sheet 4;

FIG. 13 is a diagram for illustrating the state of the metal sheet when removed from the die set with a blank holder locked at the bottom dead center;

FIG. 14 is an explanatory diagram of the state in which a member having a vertical wall portion to be formed, inclined so as to widen downward is press formed;

FIG. 15 is a schematic explanatory diagram showing one example of a configuration of a press forming die set of the present invention;

FIG. 16 is a schematic explanatory diagram showing another example of the configuration of the press forming die set of the present invention;

FIGS. 17A to 17C are schematic explanatory diagrams showing the procedure for forming a metal sheet when a die set including forming jigs 10 is used;

FIG. 18 is an explanatory diagram showing a modified example of a die set provided with only clearances CL3 and CL4;

FIG. 19 is a graph showing the relationship between the

difference between the clearances CL1 and CL2 and the flange spring angle θ when forming was carried out using a 980 MPa class cold rolled sheet steel;

FIGS. 20A and 20B are explanatory diagrams showing the product cross sectional shape for conventional forming and the product cross sectional shape when $CL2 - CL1 = 5\text{mm}$, respectively, for comparison;

FIG. 21 is a graph showing the relationship between the difference between the clearances CL1 and CL2 and the flange spring angle θ when forming was carried out using a 590 MPa class cold rolled sheet steel;

FIG. 22 is a graph showing the relationship between the forming height H and the flange spring angle θ ;

FIG. 23 is a graph showing the relationship between the forming height H and the wall warp curvature ρ ;

FIG. 24 is a graph showing the relationship between the die radius r_d and the flange spring angle θ ;

FIG. 25 is a graph showing the results of the examination on the effects inflicted upon the flange spring angle θ by the shape of a punch;

FIG. 26 is a schematic explanatory diagram showing one example of a configuration of a conventional press forming die set;

FIGS. 27A to 27C are schematic explanatory diagrams showing the product cross sectional shapes when press forming was carried out by means of respective die sets;

FIG. 28 is an explanatory diagram showing the cross

sectional shape of a product of which the wall warp has been improved by means of the die set of the present invention;

FIG. 29 is a schematic explanatory diagram showing a conventional die set when a product with an inclined vertical wall portion is formed; and

FIGS. 30A to 30C are schematic explanatory diagrams showing the product cross sectional shapes when press forming was carried out by means of respective die sets.

DETAILED DESCRIPTION OF THE PREFERRED EMBODIMENTS

The present inventors have conducted a study from various angles to solve the foregoing problems. Then, they have first acquired the following idea. In order to effectively induce the formation of the reverse bending deformed portion due to overrun even when the die radius (rd) portion is a large area, it is essential only to implement the form of a die set having a space where a material which has passed through the die shoulder, and flown to the vertical wall (sidewall) can be largely deformed between tools (between a die and a punch) during forming or during release from the die set. Thus, they further conducted a study based on such an idea, and then, they found that the foregoing object could be fairly implemented by adopting the foregoing constitution. As a result, they completed the present invention.

The constitution, and the function and effects of the present invention will be described by reference to the accompanying drawings. Incidentally, in the following

explanation, for convenience of description, explanation will be given by citing the case where hat channel members often used for the parts of the automobile body are draw formed as members to be press formed. The members to be formed in the present invention are not certainly limited to such hat channel members. Further, the forming method thereof is also not limited to the draw forming method. For example, other members and forming methods are also applicable by changing the shape of a punch in bend forming (forming) as shown in FIG. 2B.

FIG. 4 is a schematic explanatory diagram showing one example of a configuration of a press forming die set of the present invention. In the diagram, a reference numeral 1 denotes a punch; 2, a die; 3, a blank holder; 4, a metal sheet; r_d , the die radius; r_p , the punch shoulder radius; and BHF, a blank holding force. For the die set of the present invention, as shown in FIG. 4, at least a punch-die clearance CL_2 corresponding to the site (the lower part of the punch 1 shown in FIG. 4) to be formed immediately after the initial stage of forming is set wider than a punch-die clearance CL_1 corresponding to the site (the upper part of the punch 1 shown in FIG. 4) to be formed at the initial stage of forming ($CL_1 < CL_2$). Namely, with the press forming die set of the present invention, a convex portion 1a extending along the die is formed at the top part area of the punch 1 corresponding to the site to be formed at the initial stage of forming so that the clearances CL_1 and CL_2 satisfy the foregoing relationship. Incidentally, the term "initial stage of forming" denotes the

period from the start of press forming of the metal sheet 4 until a given time elapses.

With the configuration shown in FIG. 4, the convex portion 1a is formed of the curved surface. However, the present invention is not limited to such a configuration. The punches 1 of various shapes such as the punch 1 mushroom shaped in cross section, having a planar portion 1c at a part of the convex portion 1b as shown in FIG. 5A, and the punch 1 having an elongated length along the direction of axis of a convex portion 1d (i.e., whereby the time of the initial stage of forming is elongated) as shown in FIG. 5B are adoptable. Incidentally, "R5" in FIGS. 5A and 5B denotes the punch shoulder radius r_p (or the radius of the top curved surface of the convex portion 1d) set at 5 mm.

Any configuration of the die set of the present invention allows its effects to be achieved so long as the clearances CL1 and CL2 satisfy the foregoing relationship. The configurations are not limited to those shown in FIGS. 4 and 5. The object of the present invention is achieved even by the die sets of the following configurations: for example, a die set configured such that the clearance CL2 gradually widens from the site to be formed at the initial stage of forming through the site to be subsequently formed; and another die set configured such that the clearance CL2 is once widened immediately after the initial stage of forming, and then further narrowed so as to approach the clearance CL1. In short, it is essential only that at least the punch-die clearance CL2

corresponding to the site to be formed immediately after the initial stage of press forming and the punch-die clearance CL1 corresponding to the site to be formed at the initial stage of press forming satisfy the foregoing relationship.

The clearances CL1 and CL2 are conceivably set in various combinations. Generally, even when any combination was adopted, the obtained result was that the dimensional accuracy was improved than with the use of a conventional die. The present inventors conducted a study on the combination of CL1 and CL2 which most improves the dimensional accuracy.

The present inventors carried out an examination on the dimensional accuracy when a hat channel member was formed with press forming by means of the die set ($r_p = 5 \text{ mm}$) of the present invention shown in FIG. 4 using a 980 MPa class cold rolled sheet steel (thickness t : 1.2 mm) in relation to the clearances CL1 and CL2. At this step, the clearance CL1 was set at three values of (1) $t + 0.4 \text{ mm}$, (2) $t + 0.2 \text{ mm}$, and (3) $t \text{ mm}$. Whereas, the clearance CL2 was set at $CL1 + 5 \text{ mm}$ as a sufficiently large value. Further, other conditions were set as follows. Whereas, at this step, an examination was also carried out on the case where press forming (draw forming) was performed using a conventional die set shown in FIG. 2A (Clearances: $t + 0.2 \text{ mm}$, $t + 0.4 \text{ mm}$, $t + 0.6 \text{ mm}$, and $t + 0.8 \text{ mm}$).

(Press forming conditions)

Die radius (r_d): 5 mm

Forming height H (FIG. 10): 67 mm

Blank size: width 250 mm, depth 40 mm

The cross sectional shapes when press forming was carried out under respective conditions are shown in FIGS. 6A to 6C. Incidentally, when press forming was performed using the conventional die set shown in FIG. 2A (conventional forming), there was no difference in amount of dimensional accuracy defect such as "wall warp" according to the clearances. However, the cross sectional shape at a clearance of $t + 0.8 \text{ mm}$ is as shown in FIG. 3B, where both of the wall warp and the angle change occur, and the flange spring angle θ shows a value as large as 48° .

On the other hand, FIG. 6A shows the cross sectional shape for the clearance CL1 set at $(t + 0.4 \text{ mm})$, and shows the situation where the dimensional accuracy has been improved largely than with conventional forming, but "wall warp" slightly remains. However, for the clearance CL1 set at $(t + 0.2 \text{ mm})$ [FIG. 6B], the effects of wall warp and reverse warp cancel out each other, which allows "wall warp" $\doteq 0$. However, in this case, the situation has been such that flange spring caused by the angle change defect at the punch shoulder portion still remains.

Further, for the clearance CL1 reduced to t (corresponding to the sheet thickness), the effect of overrun is intensively produced, so that the sidewall portion is inwardly warped [FIG. 6C]. The inward warp and the angle change at the punch shoulder cancel out each other, which can implement a flange spring angle $\theta = 0^\circ$. Incidentally, the shape of the sidewall portion in this case is an inwardly warped shape, and hence it is different from the target shape.

These results indicate the following consideration. Namely, depending upon whether importance is attached to the shape of the sidewall portion or importance is attached to the spring of the flange surface, the clearance CL1 is finely controlled within a range of $t \leq CL1 \leq t + 0.2$ (mm). As a result, optimum dimensional accuracy can be obtained.

The present inventors also carried out an examination on some materials for the effect of the clearance CL1 by changing the clearance CL1 within a range of $0.8t$ to $2.0t$. The conditions other than the kind of the material and the sheet thickness t at this step are the same as described above (therefore, clearance $CL2 = CL1 + 5$ mm). The results are shown in Table 1, which indicates as follows. For all the materials, optimum dimensional accuracy is obtained by controlling the clearance CL1 within a range of $0.8 \times t \leq CL1 \leq 1.2 \times t$. Incidentally, the reason why the lower limit of the clearance CL1 is set at $0.8 \times t$ is as follows. When the clearance CL1 becomes narrower than this, the sheet thickness becomes too thin, which may reduce the strength characteristic as the member.

[Table 1]

Material	Evaluation item	Clearance CL1				
		0.8×t	1.0×t	1.2×t	1.4×t	1.6×t or more
5000 series aluminum sheet (t:1.0mm)	Wall warp curvature	◎	◎	○	○	△
	Flange spring angle	◎	◎	○	○	△
Pure titanium sheet JIS Class 1 (t:1.0mm)	Wall warp curvature	◎	◎	○	○	△
	Flange spring angle	◎	◎	○	○	△
440 MPa cold rolled sheet steel (t:1.2mm)	Wall warp curvature	◎	◎	○	○	△
	Flange spring angle	◎	◎	○	○	△
590 MPa cold rolled sheet steel (t:1.2mm)	Wall warp curvature	◎	○	◎	○	△
	Flange spring angle	◎	◎	○	○	△
980 MPa cold rolled sheet steel (t:1.0mm)	Wall warp curvature	○	○	◎	○	△
	Flange spring angle	○	◎	○	○	△
980 MPa cold rolled sheet steel (t:1.2mm)	Wall warp curvature	○	○	◎	○	△
	Flange spring angle	○	◎	○	○	△
980 MPa cold rolled sheet steel (t:1.4mm)	Wall warp curvature	○	○	◎	○	△
	Flange spring angle	○	◎	○	○	△
980 MPa cold rolled sheet steel (t:1.6mm)	Wall warp curvature	○	○	◎	○	△
	Flange spring angle	○	◎	○	○	△

◎ : Conditions under which the defective forming amount is less than 10 % of that for conventional forming;

○ : Conditions under which the defective forming amount is 10 % or more and less than 50 % of that for conventional forming;

△ : Conditions under which the defective forming amount is 50 % or more and less than 100 % of that for conventional forming; and

× : Conditions under which the defective forming amount is equal to or more than that for conventional forming.

Incidentally, when the die set shown in FIG. 4 is used, and the clearance CL1 is set at $(t + 0.2 \text{ mm})$, as shown in FIG. 6B, the situation is such that "wall warp" $\cong 0$ has been implemented, but the spring of the flange still remains. Consequently, the present inventors also studied the method capable of minimizing the flange spring angle θ while implementing "wall warp" $\cong 0$.

As a result, it has also been found as follows. As shown in FIG. 7, the blank holder 3 is allowed to wait at a position lower than the top surface of the punch 1 at the time of start of forming (in the diagram, ΔH denotes the wait height). This can minimize the flange spring angle θ . Namely, in general, with conventional press forming, first, the metal sheet 4 is interposed and held between the die 2 and the blank holder 3, and then forming is started (for this procedure, see FIGS. 9A and 9B). The blank holder 3 is set in the state shown in FIG. 7 at this time of start of forming, and then forming is started, which implements the reduction in punch shoulder angle change. As a result, it is possible to minimize the flange spring angle θ . Therefore, for carrying out press forming using the die set of the present invention, the clearance CL1 is set within a proper range to implement "wall warp" $\cong 0$, and the wait height ΔH shown in FIG. 7 is appropriately set to reduce the angle change. As a result, it is possible to obtain a press formed product

more excellent in dimensional accuracy.

The reason why the foregoing effect can be obtained by starting press forming in the state shown in FIG. 7 is conceivable as follows. Namely, when the blank holder 3 is allowed to wait at a position lower than the punch top surface at the time of start of forming, bend forming by the punch 1 and the die 2 acts on the metal sheet 4 during the initial stage of forming until the blank holder 3 and the die 2 approach each other. During the bend forming, material restraint due to holding by the blank holder 3 does not work. Therefore, as shown in FIG. 8 (partially enlarged diagram), overrun becomes more likely to occur. For this reason, the material (metal sheet 4) becomes likely to wind over a wide range of the punch shoulder (i.e., the bending angle of the metal sheet 4 becomes larger than 90°). Thus, the bending angle approaches 90° close to ideal by spring back after release from the die set.

By the completion of the die set of the foregoing configuration, it was possible to implement the improvement of the dimensional accuracy. However, it was clarified as follows. The factor affecting the dimensional accuracy is not only overrun during forming. However, the amplification of overrun upon release from the die set and reverse bending upon passing the punch shoulder portion (e.g., the convex portion 1a of FIG. 4) also affect the dimensional accuracy. Such a situation will

be described by reference to the drawings.

FIGS. 9A and 9B are explanatory diagrams each showing the state of the die set at the time of start of forming. First, as shown in FIG. 9A, the metal sheet 4 is interposed and held between the die 2 and the blank holder 3, so that the top end of the punch 1 is being in contact with the surface of the metal sheet 4. Then, the die 2 is caused to move downward with the metal sheet 4 interposed between the die 2 and the blank holder 3, so that forming of the metal sheet 4 is started by the operation of the punch 1 [FIG. 9B]. The die 2 keeps moving downward, thereby to perform forming.

FIG. 10 is an explanatory diagram showing the state in which forming of the metal sheet 4 has been completed (forming bottom dead center). In this state, the blank holder 3 has gone downward completely, and the forming of the vertical wall portion of the metal sheet 4 has completely undergone forming (in the diagram, H denotes the forming height). Then, in this state, overrun occurs at the vertical wall lower part 4a of the metal sheet 4.

Subsequently, the die 2 is caused to move upward with the metal sheet 4, which has completely undergone forming, interposed between the die 2 and the blank holder 3 for release. As a result, as shown in FIG. 11, the narrow clearance at the punch shoulder portion (convex portion 1a) results in

resistance to release, the overrun occurred at the vertical wall lower part 4a of the metal sheet 4 is further amplified. Then, the die 2 further keeps moving upward (being released), so that as shown in FIG. 12A, reverse bending occurs at the vertical wall lower part 4a when the vertical wall lower part 4a passes the vicinity of the punch shoulder portion (convex portion 1a). For the member which has undergone the step of [FIG. 12B] and has been completely released from the die set, the wall warp of the vertical wall portion is improved by this effect of reverse bending. Namely, as shown in FIGS. 6B and 6C, by the control of reverse bending, it is possible to entirely eliminate the wall warp, or to cause the wall to tend to undergo inward warp.

For the release from the die set shown in FIGS. 11 and 12A and 12B, there is shown the case where upon upward movement of the die 2, the blank holder 3 follows it, and also moves upward [the result shown in FIG. 6 is also intended for this case]. However, there is also another case of forming where the blank holder 3 is locked at the forming bottom dead center during release from the die set, and does not move upward together with the die 2 during release from the die set. There are relatively few cases where forming is performed with the blank holder 3 locked at the bottom dead center during release from the die set from the viewpoint of the productivity of press forming.

When the release is carried out with the blank holder 3 locked at the bottom dead center, the metal sheet 4 is released from the die set, and comes in the wall warp state as shown in FIG. 13. Thus, the function of amplification of overrun during release (FIG. 11) and the effect of generating reverse bending upon passing through the punch shoulder (FIG. 12) are not produced, resulting in a small wall warp improvement effect.

On the other hand, as shown in FIG. 14, in the case where a member having a vertical wall portion inclined so that the vertical wall portion to be formed widens downward (in the diagram, θ_1 denotes the angle of inclination of the vertical wall portion) is press formed, even when the blank holder 3 is caused to move upward together during release from the die set, the clearance between the punch shoulder portion and the die widens as the die 2 moves upward. Thus, the function of amplification of overrun does not sufficiently occur with approach to the material in the vicinity of the die shoulder, and the effects of the present invention may not be produced sufficiently. Namely, the wall warp is improved at the portion having a narrow clearance from the punch shoulder during release. Whereas, wall warp tends to be likely to occur at the portion having a wide clearance from the punch shoulder (vertical wall lower part) during release.

Thus, for solving the foregoing problem, the present

inventors have further conducted an additional study with the aim of implementing a die set structure capable of satisfying the following requirements: (1) overrun and reverse bending deformation can be implemented only during forming; (2) overrun and reverse bending deformation can be implemented along the overall length of the vertical wall regardless of the angle of inclination (θ_1 shown in FIG. 14) of the vertical wall, and other requirements.

As a result, it has been clarified as follows. A die set is configured to have a forming jig which moves in synchronism with a die while keeping the relative position to the die during forming, and forms the vertical wall portion of a metal sheet. For the forming jig, the clearance CL4 between the forming jig and the die in the vicinity of the die shoulder is set so as to be wider than the clearance CL3 between the forming jig and the die in the forming area other than the vicinity of the die shoulder ($CL3 < CL4$). As a result, the foregoing disadvantage is resolved, and it is possible to further enhance the dimensional accuracy in press forming of the metal sheet.

FIG. 15 is a schematic explanatory diagram showing one example of a configuration of a press forming die set of the present invention completed from the foregoing viewpoint. It is similar in basic configuration to FIG. 4, and the same reference numerals and characters are given to the

corresponding parts, so that overlapping description is avoided. With this configuration, the forming jigs 10 for forming the vertical wall portions of the metal sheet 4 (press formed product) are provided one each on opposite inner sides (sides facing the punch 1) of the blank holders 3 in such a manner as to be each integral with its corresponding blank holder 3. Each forming jig 10 has a protrusion 10a for forming the metal sheet 4 from inside of the metal sheet 4 on its top end. Then, each forming jig 10 is configured to move in synchronism with the die 2 while keeping the relative position to the die 2 during forming, so that the clearance (CL3) between the forming jig (i.e., the protrusion 10a) and the die 2 is constant. Further, it is configured such that the clearance CL4 between the forming jig 10 and the die 2 in the vicinity of the die shoulder is set wider than the clearance CL3 (i.e., the clearance in the forming area other than the vicinity of the die shoulder). By adopting such a die set configuration, overrun and reverse bending deformation function are further achieved by the forming jigs 10 during press forming.

FIG. 16 is a schematic explanatory diagram showing another example of a configuration of a press forming die set in accordance with the present invention. This configuration is for the case where the present invention is applied to the press forming of a material with a vertical wall portion having

an inclined angle. Other portions are equal to those of the die set configuration shown in FIG. 15. Also by adopting such a configuration, the foregoing effects of the present invention are achieved.

Incidentally, the respective clearances CL3 and CL4 are preferably set so as to satisfy the following relationships of the expressions (3) and (4), respectively, for the same reason as that for the clearances CL1 and CL2 (in the expressions, t denotes the thickness). Namely, the respective clearances CL3 and CL4 accomplish the roles of (1) inducing overrun; (2) amplifying overrun; and (3) applying reverse bending, as with the clearances CL1 and CL2. Whereas, as apparent from FIG. 23, the expressions (1) and (2) are not affected by the forming height H . For this reason, even when the protrusion 10a shown in FIG. 15 is in the vicinity of the die shoulder, the configuration can be conceivably controlled by the same relationship of the expressions (1) and (2) [i.e., the expressions (3) and (4)] for the clearances as with the punch shoulder 10a of FIG. 10.

$$0.8 \times t \leq CL3 \leq 1.2 \times t \quad \cdots (3)$$

$$CL4 \geq CL3 + t \quad \cdots (4)$$

Therefore, when the die set structures of FIGS. 15 and 16 are adopted, the effects of the present invention are achieved only by defining the clearances CL3 and CL4 so as to

meet the proper relationship, without accurately defining the relationship of CL1 and CL2. The clearances CL1 and CL2 may be certainly defined so as to satisfy the relationship of the expressions (1) and (2) even when such a configuration is adopted.

The procedure for forming a metal sheet when using a die set having forming jigs will be described by reference to drawings. First, at the time of start of forming, as shown in FIG. 17A, the metal sheet 4 is not being interposed between the die 2 and the blank holder 3 by the presence of the forming jigs 10, but a prescribed space is present between the blank holder 3 and the metal sheet 4. Then, forming of the metal sheet 4 is started by the die 2, so that the metal sheet 4 undergoes bend forming. At this step, the blank holder 3 still does not operate [FIG. 17B]. Subsequently, the die 2 is caused to move downward with the metal sheet 4 interposed between the die 2 and the blank holder 3 (the blank holder 3 also follows the movement, and moves downward), thereby to carry out forming of the metal sheet 4 [FIG. 17C].

With the die sets shown in FIGS. 15 and 16, provision of the forming jigs 10 effectively generates overrun and reverse bending to the metal sheet 4 during forming. As shown in FIGS. 17A to 17C, upon starting of forming using such a die set, the same function as that in the state where, using a die set not

including a forming jig 10, forming has been started with the blank holder 3 waiting is achieved (FIGS. 7 and 8), so that the effect of reducing the flange spring angle is also produced.

Incidentally, when the clearances CL3 and CL4 are properly defined, the effects of the present invention are achieved even if the clearances CL1 and CL2 are not accurately defined. For this reason, it is also possible to achieve such a die set design in which only the clearances CL3 and CL4 are provided, if required. A modified example of a die set configured from such a viewpoint is shown in FIG. 18. This die set is intended for manufacturing a formed product having an incline vertical wall portion. The punch 1 is not provided with a convex portion 1a on its top, and is formed of a vertical wall. Further, the forming surface of the die 2 is formed in an inclined surface because the forming jig inserts around the lower part of the punch 1. Then, by properly setting the clearances CL3 and CL4 between the forming jig 10 and the die 2, a vertical wall portion having an angle of inclination of θ_1 is formed by the action of the forming jig 10 and the die 2. The effects of the present invention are also achieved by the die set of such a configuration.

Below, the functions and the effects of the present invention will be more specifically shown by way of examples. However, the following examples should not be construed as

limiting the scope of the invention. The present invention can be practiced with appropriate modification within a scope not departing from the gist described above or later, any of which is included in the technical range of the present invention.

[Examples]

[Example 1]

As for the dimensional accuracy when a hat channel member was formed with press forming by means of the die set ($r_p = 5$ mm) of the present invention shown in FIG. 4 using a 980 MPa class cold rolled sheet steel (thickness t : 1.2 mm), the clearance CL2 was changed, and the effects thereof were examined. At this step, as the clearance CL1, $CL1 = t$, which enabled the spring angle of the flange surface to be controlled to 0° , was adopted. Whereas, the clearance CL2 was varied to 6 values of (1) $CL1 + 0$ mm, (2) $CL1 + 0.5$ mm, (3) $CL1 + 1.7$ mm, (4) $CL1 + 2.8$ mm, (5) $CL1 + 3.9$ mm, and (6) $CL1 + 5$ mm. Further, the other conditions (die radius r_d , forming height H , blank holding force, and the like) were set at the same values as described above. The flange spring angles θ in the respective cases (1) to (6) were as follows.

(Flange spring angle θ)

(1) 48° , (2) 26.9° , (3) 4.3° , (4) -1.3° , (5) -1.0° , (6) -1.7°

The relationship between the difference between the

clearances CL2 and CL1 (CL2-CL1: mm) and the flange spring angle θ is shown in FIG. 19. The product cross sectional shape for conventional forming (CL2-CL1 = 0 mm) and the product cross sectional shape when CL2-CL1 = 5 mm are shown for comparison in FIGS. 20A and 20B, respectively. As apparent from these results, when $CL2-CL1 \geq t$ (i.e., $CL2 \geq CL1 + t$), the flange spring angle θ is almost stable in the vicinity of 0° .

The same examination was carried out using a 590 MPa class cold rolled sheet steel (thickness t : 1.2 mm) in the same manner as described above. As a result, the flange spring angles θ in the respective cases (1) to (6) were as follows.

(Flange spring angle θ)

(1) 25.5° , (2) 7.5° , (3) -0.6° , (4) -0.7° , (5) 0.0° , (6) -0.4°

The relationship between the difference between the clearances CL2 and CL1 (CL2-CL1: mm) and the flange spring angle θ at this step is shown in FIG. 21, indicating that almost the same tendency as with FIG. 19 is observable.

Incidentally, it is conceivable that the dimensional accuracy is dependent upon some other influence factors in the die set [forming height H (FIG. 10), die radius r_d , punch top part shape, and the like]. The present inventors conducted a study on these factors. As a result, it has been shown that these factors do not affect the effects of the present invention

so much. Then, the results of the study will be shown.

As for the dimensional accuracy when a hat channel member was formed with press forming by means of the die set of the present invention shown in FIG. 4 using a 980 MPa class cold rolled sheet steel (thickness t : 1.2 mm), the forming height H was changed, and the effects thereof were examined. The forming height H at this step was varied within a range of (1) 30 mm, (2) 40 mm, (3) 50 mm, (4) 60 mm, and (5) 67 mm, by changing the bottom dead center of the die.

As for the clearances $CL1$ and $CL2$, under the conditions of $CL1 = t$ (mm) and $CL2 = CL1 + 5$ (mm), which enabled the implementation of flange spring angle $\theta \cong 0^\circ$ in FIG. 19, the effect of the forming height H on the flange spring angle θ was examined. Further, under the conditions of $CL1 = t + 0.2$ (mm) and $CL2 = CL1 + 5$ (mm), which enabled the implementation of wall warp $\cong 0$ (mm) in FIG. 6B, the effect of the forming height H on the wall warp was examined.

The relationship between the forming height H and the flange spring angle θ is shown in FIG. 22. The relationship between the forming height H and the wall warp curvature ρ is shown FIG. 23. Incidentally, the wall warp curvature ρ is the value expressed as $1/d$ where d denotes the warp radius. As apparent from these results, the amount of dimensional defect is large for conventional forming. Whereas, for the present

invention, the defect amount is small and no effect of the forming height H arises at all.

As for the dimensional accuracy when a hat channel member was formed with press forming by means of the die set of the present invention shown in FIG. 4 using a 980 MPa class cold rolled sheet steel (thickness t : 1.2 mm), the die radius r_d was changed, and the effects thereof were examined. The die radius r_d at this step was varied within a range of (1) 5 mm, (2) 10 mm, and (3) 15 mm (forming height H was 67 mm).

The relationship between the die radius r_d and the flange spring angle θ is shown in FIG. 24, indicating as follows. Even when the die radius r_d is increased up to 15 mm, the effects of the present invention can be kept, and flange spring angle $\theta \cong 0$ is achieved. In contrast, when a conventional die set has been used (conventional forming), the die radius r_d largely affects the flange spring angle θ . Namely, it is indicated that use of the die set of the present invention eliminates the necessity of controlling the die radius r_d within a narrow range.

As described above, the shape of the top part of the punch has no particular restriction so long as the relationship of the clearances $CL1$ and $CL2$ defined in the present invention is satisfied. As for the dimensional accuracy (flange spring angle θ) when a hat channel member was formed with press forming

by means of the punches of various top part shapes shown in FIGS. 4 and 5 using a 440 MPa class cold rolled sheet steel (thickness t : 1.2 mm), the effects of the top part shapes of the punches on the dimensional accuracy (flange spring angle θ) were examined. The other conditions at this step were set as follows.

(Press forming conditions)

Clearance: $CL1 = t$ (mm), $CL2 = CL1 + 5$ (mm)

Die radius rd : 5 mm

Punch shoulder radius rp : 5 mm

Forming height H (FIG. 10): 67 mm

Blank size: width 250 mm, depth 40 mm

Blank holding force (BHF): 10 KN

The results are shown for comparison with conventional forming in FIG. 25. As apparent from the results, a difference is slightly caused according to the shape of the top part of the punch. However, with any shape shown in FIGS. 4 and 5, the effects of the present invention are sufficiently produced. However, when the length along the direction of axis in the convex portion of the top part of the punch (i.e., the length of the portion corresponding to the portion formed at the initial stage of forming) [FIG. 5B] is elongated, the effects of the present invention are affected to be decreased. Therefore, it is necessary to set the length at a proper length.

The proper clearances specified above were set [$CL1 = t$ (mm), $CL2 = CL1 + 5$ (mm)]. A 590 MPa class hot dip zinc plated sheet steel which had not been used above (thickness t : 1.4 mm) was subjected to press forming to manufacture a hat channel member (the other conditions are the same as described above). As a result, it has been shown that a hat channel member with favorable dimensional accuracy is formed.

[Example 2]

As for the dimensional accuracy when a hat channel member was formed with press forming by means of the die set of the present invention shown in FIG. 4 ($rp = 5$ mm) using a 780 MPa class cold rolled sheet steel (thickness t : 1.2 mm), the wait height ΔH of the blank holder (FIG. 7) was varied ($\Delta H = 0$ mm and $\Delta H = 20$ mm), and the effects thereof were examined. The press forming conditions at this step were as follows.

(Press forming conditions)

Clearance: $CL1 = t + 0.2$ (mm), $CL2 = CL1 + 5$ (mm)

Die radius rd : 5 mm

Punch shoulder radius rp : 5 mm

Forming height H (FIG. 10): 67 mm

Blank size: width 250 mm, depth 40 mm

Blank holding force (BHF): 10 KN

Wait height ΔH : 0 mm (no wait), 20 mm

At this step, an examination was also carried out on the

dimensional accuracy when a hat channel member was formed by a conventional procedure (see, FIGS. 9A and 9B, and 10) by means of a conventional die set (the one having no convex portion 1a formed on the top of the punch) shown in FIG. 26 (the press forming conditions were the same as described above except that the clearance $CL = 1.5 \text{ mm}$). Further, in any case, the blank holder 3 was caused to move upward together during release from the die set.

The cross sectional shapes of the products press formed by respective die sets are shown in FIG. 27A to 27 C. Out of these, FIG. 27A shows the shape when the product has been formed using a conventional die set, indicating that wall warp and angle change mostly remains, and the flange spring angle θ have been also increased. In contrast, FIG. 27B shows the cross sectional shape of the product when using the die set of the present invention (wait height $\Delta H = 0 \text{ mm}$), indicating that the angle change is large, but the wall warp and the flange spring angle θ have been reduced. Further, FIG. 27C shows the one in the case where using the die set of the present invention, forming was started with the blank holder waiting (wait height $\Delta H = 20 \text{ mm}$), indicating that both the wall warp and the angle change have been reduced, and the flange spring angle θ has been also further reduced.

[Example 3]

The dimensional accuracy when each hat channel member was formed with press forming by means of the die set shown in FIG. 4 and the die set (the one including forming jigs 10) shown in FIG. 15 using a 780 MPa class cold rolled sheet steel (thickness t : 1.2 mm) was examined for the following respective cases (A) and (B):

(A) The case where the blank holder is caused to move upward together during release from the die set; and

(B) The case where the blank holder is locked at the bottom dead center during release from the die set.

The common press forming conditions at this step were as follows.

(Press forming conditions)

Die radius r_d : 5 mm

Punch shoulder radius r_p : 5 mm

Forming height H (FIGS. 10 and 15): 67 mm

Blank size: width 250 mm, depth 40 mm

Blank holding force (BHF): 10 KN

The clearances $CL1$ and $CL2$ of the die set shown in FIG. 4 were set at $CL1 = 1.2$ mm (= thickness) and $CL2 = CL1 + 5$ mm, respectively. The clearances $CL1$ to $CL4$ of the die set shown in FIG. 15 were set at $CL1 = 1.2$ mm (thickness), $CL2 = 15$ mm, $CL3 = 1.2$ mm (thickness), and $CL4 = CL3 + 3$ mm, respectively. Further, in the die set shown in FIG. 15, the height from the

blank holder top surface to the protrusion 10a was set at 11 mm, and the shoulder radius of the protrusion 10a was set at 3 mm.

At this step, an examination was also carried out on the dimensional accuracy when a hat channel member was formed by means of the conventional die set shown in FIG. 26 in each of the cases (A) and (B) (the press forming conditions were the same as described above except that the clearance $CL = 1.5$ mm).

As a result, when forming was carried out by means of a conventional die set, in any of the cases (A) and (B), the wall warp and the angle change mostly remained, and the flange spring angle θ was also increased [see, FIG. 27A].

In contrast, when forming was carried out by means of the die set shown in FIG. 4 under the conditions of the case (A), a formed product of which the wall warp had been improved as shown in cross section in FIG. 28 was obtained. Whereas, when forming was carried out under the conditions of the case (B), the wall warp occurred, resulting in the shape shown in FIG. 27A. Whereas, when the die set shown in FIG. 15 was used, even in any of the cases (A) and (B), the wall warp was improved, so that the formed product as shown in FIG. 28 was obtained.

[Example 4]

An examination was carried out on the dimensional accuracy when each hat channel member was formed with press

forming by means of the die set shown in FIG. 14 and the die set (the one with a vertical wall portion having an angle of inclination) shown in FIG. 16 using a 780 MPa class cold rolled sheet steel (thickness t : 1.2 mm).

The common press forming conditions at this step were as follows.

(Press forming conditions)

Die radius r_d : 5 mm

Punch shoulder radius r_p : 5 mm

Angle of inclination θ_1 : 3°

Forming height H (FIGS. 14 and 16): 67 mm

Blank size: width 250 mm, depth 40 mm

Blank holding force (BHF): 10 KN

The clearances CL_1 and CL_2 of the die set shown in FIG. 14 were set at $CL_1 = 1.2$ mm (= thickness) and CL_2 (the narrowest portion immediately under the top part of the punch) = $CL_1 + 5$ mm, respectively. Whereas, the clearances CL_1 to CL_4 of the die set shown in FIG. 16 were set at $CL_1 = 1.2$ mm (thickness), CL_2 (the narrowest portion immediately under the top part of the punch) = 15 mm, $CL_3 = 1.2$ mm (thickness), and $CL_4 = CL_3 + 3$ mm, respectively. Further, in the die set shown in FIG. 16, the height from the blank holder top surface to the protrusion 10a was set at 11 mm, and the shoulder radius of the protrusion 10a was set at 3 mm.

At this step, an examination was also carried out on the dimensional accuracy when a hat channel member was formed by means of a conventional die set (the one with a vertical wall portion having an angle of inclination θ_1 of 3°) shown in FIG. 29 (the press forming conditions were the same as described above except that the clearance $CL = 1.5 \text{ mm}$). Further, the blank holder 3 was caused to move upward together during release from the die set.

The cross sectional shapes of the products press formed by respective die sets are shown in FIGS. 30A to 30C. Out of these, FIG. 30A shows the shape when the product has been formed using a conventional die set, indicating that the wall warp and the angle change mostly remains, and that the flange spring angle θ has been also increased. In contrast, FIG. 30B shows the cross sectional shape of the product when using the die set shown in FIG. 14, indicating that the wall warp partially remains, but has been largely improved. Further, FIG. 30C shows the cross sectional shape of the product when using the die set shown in FIG. 16, indicating that the wall warp has been improved along the overall length of the vertical wall.

These results are for the case where the blank holder was caused to move upward together during release from the die set. It has been confirmed as follows. When the die set shown in FIG. 16 is used, the same results [FIG. 30C] are obtainable even

when the blank holder is locked at the bottom dead center during release from the die set.